A detailed breakdown of the various components and templates, found in the Template Library, is shown below. Enhanced features in the template graphics have been highlighted in blue. These are features that may be hidden when the component/template is selected through the Corridor Modeler (CM) program.

The format for the template naming convention is as follows:

E_#DP_SSSS_CCCC_BBBB_WWWW

- **E** = Enhanced, or altered from the original intent
- **#PD** = # = number of lanes, D is added for Divided multilane
- **P** = pavement type,
- **S, C, B, and W** are for Shoulder, Curb, Barrier, and Wall sections, respectively

The four characters in each grouping represent the location from left to right: left outside, left median, right median, right outside

- **Pavement:** P = PCC, H = HMA
- **Shoulders:** E = Earth, G = Granular, P = PCC, H = HMA, C = Composite
- **Curbs:** T = Standard, S = Sloped, I = Integral
- **Barriers:** 0 = BA-100, 2 = BA-102, 3 = BA-103
- **Walls:** M = MSE, C = CIP, S = Soil Nail, N = Noise Wall

**NOTE:** For additional information on Point Names and Locations, Template Names, and Component Names, see file Corridor Modeler Naming and Symbology.xls

Templates Enhanced

**E_1P_GG -- -- (CL Left) & (CL Right)**

**E_2H_G--G_----_----**

**E_2P_G--G_----_----**

**E_3P_G--G_----_----**
E_1P_GG__-__

\[\begin{align*}
E & = \text{Enhanced, to include Possible Outside Auxiliary Lanes} \\
1P & = 1 \text{ Lane PCC paved} \\
GG & = \text{Granular shoulder on both sides}
\end{align*}\]
E_2H_G—G---------

E = Enhanced, to include Possible Outside Auxiliary Lanes
2H = 2 Lane HMA paved
G—G = Granular shoulder on both sides

“Click” for video on Corridor Modeler Point Controls
E_2P_G—G_----_----

E = Enhanced, to include Possible Outside Auxiliary Lanes
2P = 2 Lane PCC paved
G—G = Granular shoulder on both outsides
E_3P_G—G_----_----

E = Enhanced, to include Possible Outside Auxiliary Lanes, Center Turn Lane, and Paved Shoulders
3P = 3 Lane PCC paved
G—G = Granular shoulder on both outsides

“Click” for video on Corridor Modeler Point Controls